

Substitute for Form P10-875

Application of Docket Number

Application of Docket Number
10/662998

{Column 1} {Column 2}

SMALL ENTITY	
RATE (\$)	FEE (\$)
25 :	
100 :	

/ CR

OTHER THAN
SMALL ENTITY

RATE (\$)	FEE (\$)
x 50 :	
x 200 :	

* If the difference in columns 1 is less than zero enter 0 in column 2

Controlled by _____

AMENDMENT A	5/15/06	CLAIMS REMARKS: AFTER AMENDMENT		FIGURE NUMBER PREVIOUSLY PAID FOR:	FIGURE C-100
	100%	24	100%	24	
	100%	3	100%	3	

SMALL ENTITY

STATE (S)	ADD: 1101466 FEE (S)
.25	
.100	

CR

OTHER THAN
SMALL ENTITY

RATE (\$)	ADDITIONAL FEE (\$)
• 50	
• 200	

TOTAL
ADDITIONAL FEE

9-14-06

AMENDMENT B	CLARIFICATION REMARKS DATE AMENDMENT		REVISION	REVISION
			DATE REVISION	DATE REVISION
Total	39		24	15
Excluded by the Board	5		3	2
Information Supplied by the Board				
FIRST PUBLISHED BY THE BOARD OF THE ...				

18.9.

DATE	4001 TODAY FEE (\$)
1	
2	
3	
4	
5	

RATE IS	ADDITIONAL FEE IS
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RATE IS	ADDITIONAL FEE IS
50	750
200	400
1-11-10 1-11-10	1150

25, 36, 46, 55, 56,

1. The invention relates to a method of determining the position of a point in space by means of a system of three cameras. The method consists in taking three photographs of the point from three different positions and in determining the position of the point by means of the three photographs.

2. The invention also relates to a system of three cameras for determining the position of a point in space. The system consists of three cameras arranged in a triangle and of a system of three lenses for focusing the images of the point on the film of the three cameras.

3. The invention also relates to a method of determining the position of a point in space by means of a system of three cameras. The method consists in taking three photographs of the point from three different positions and in determining the position of the point by means of the three photographs.

4. The invention also relates to a system of three cameras for determining the position of a point in space. The system consists of three cameras arranged in a triangle and of a system of three lenses for focusing the images of the point on the film of the three cameras.

5. The invention also relates to a method of determining the position of a point in space by means of a system of three cameras. The method consists in taking three photographs of the point from three different positions and in determining the position of the point by means of the three photographs.

6. The invention also relates to a system of three cameras for determining the position of a point in space. The system consists of three cameras arranged in a triangle and of a system of three lenses for focusing the images of the point on the film of the three cameras.

7. The invention also relates to a method of determining the position of a point in space by means of a system of three cameras. The method consists in taking three photographs of the point from three different positions and in determining the position of the point by means of the three photographs.

8. The invention also relates to a system of three cameras for determining the position of a point in space. The system consists of three cameras arranged in a triangle and of a system of three lenses for focusing the images of the point on the film of the three cameras.

9. The invention also relates to a method of determining the position of a point in space by means of a system of three cameras. The method consists in taking three photographs of the point from three different positions and in determining the position of the point by means of the three photographs.

10. The invention also relates to a system of three cameras for determining the position of a point in space. The system consists of three cameras arranged in a triangle and of a system of three lenses for focusing the images of the point on the film of the three cameras.